

# Traveling-Wave-Based Fault Location in Electrical Distribution Systems with Digital Simulations

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## Abstract

*Traveling-wave-based fault location in electrical distribution systems is an important safeguard for the distribution network reliability. The effectiveness of the methods is verified directly in power grid in the early stages, while different fault types can't appear in a short time. And normal dynamic physical simulation cannot meet the teaching demand either because of the limitation of transmission line model and other factors. So PSCAD/EMTDC and MATLAB are used to illustrate the fault location methods in this paper, which can promote the traveling-wave-based fault-location technology. Meanwhile, the traveling-wave-based fault-location method based on characteristic frequencies is analyzed in this paper.*

**Keywords:** characteristic frequency, fault location, transmission line model, traveling wave

## 1. Introduction

Fault location in the electrical distribution systems (EDSs) is very important for the secure and stable operation [1]. In the past decade, fault location in EDSs has been extensively investigated and several approaches have been proposed, which includes faulty feeder identification [2], fault section location [3] and fault position location [1]. With the development of smart distribution grids, fault location becomes more and more important.

The proposed fault location methods can be grouped into two categories: 1) methods based on the impedance measurement [4]-[7]; 2) methods based on the traveling waves [8]-[12].

Traveling-wave-based fault-location methods (TWFLMs) have the advantages of less influence by saturation characteristic of current transformer, fault resistance, fault type and the operating mode of system, so they have been successfully applied into transmission networks [13]. However, they can hardly be applied into EDSs because the feeders usually include many laterals.

Comparing with the wide investigation of TWFLMs, test technology of traveling-wave fault location falls behind obviously. Early verification of traveling-wave fault-location technology is difficult to operate directly in power grid, while different fault types can't appear in a short time [14]. At the same time, normal dynamic physical simulation can't meet the test demand because of the limitation of transmission line model and other factors [15]. Therefore, theoretical research and equipment development of traveling-wave fault location seriously depend on digital simulation [16].

To overcome the problems, PSCAD/EMTDC, which is widely used in electromagnetic transient simulations [16]-[17], and Matlab are used to study the TWFLMs. Meanwhile, a novel fault location method based on characteristic frequencies of the recorded transient wave is proposed.

## 2. Review of Traveling-wave-based Fault-location Methods

Generally, TWFLMs can be grouped into the following main categories: 1) methods based on wave-front identification (single-ended algorithm [18], two-ended algorithm [19] and network-based algorithm [20]); 2) algorithms based on characteristic frequencies of the recorded traveling wave [10]-[12].

In this paper, take the fault-location methods based on characteristic frequencies as an example, PSCAD/EMTDC and MATLAB are used to show the effectiveness of the methods.

When the end of the transmission line is set as the starting point of the calculation distance  $x$ , the voltage can be represented in the time domain by [21]

$$u = \sqrt{2}U_0^+ e^{-\alpha x} \cos(\omega t - \beta x + \psi_+) + \sqrt{2}U_0^- e^{\alpha x} \cos(\omega t + \beta x + \psi_-) = u_+ + u_- \quad (1)$$

$u_+$  denotes the incident wave and  $u_-$  represents the reflected wave. Assuming the impedance of the load equals  $Z_2$ , the reflection coefficient at the end ( $x=0$ ) for the voltage traveling wave is

$$\rho = \frac{U_0^-}{U_0^+} = \frac{Z_2 - Z_c}{Z_2 + Z_c} \quad (2)$$

As shown in Figure 1, Ref. [10] proposed the principle of the characteristic frequencies. If the measuring point is placed at bus A and the three-phase short-circuit fault occurs at middle of line DF, the traveling wave will propagate back and forth in the paths A-B, A-B-D, A-B-C, A-B-D-E and A-B-D- $f$  ( $f$  is the fault point). So the characteristic frequencies will exist in the recorded transient signal at bus A and can be calculated by

$$f_{p,i} = \frac{v_i}{n_p L_p} \quad (3)$$

Where:  $u_i$  denotes the velocity of the  $i$ -mode traveling wave;  $L_p$  represents the propagation length of the path  $P$  and  $n_p$  depends on the reflection coefficients at both ends of the path. If the polarities of the reflection coefficients at both ends are the same,  $n_p$  equals 2. Otherwise  $n_p$  equals 4.

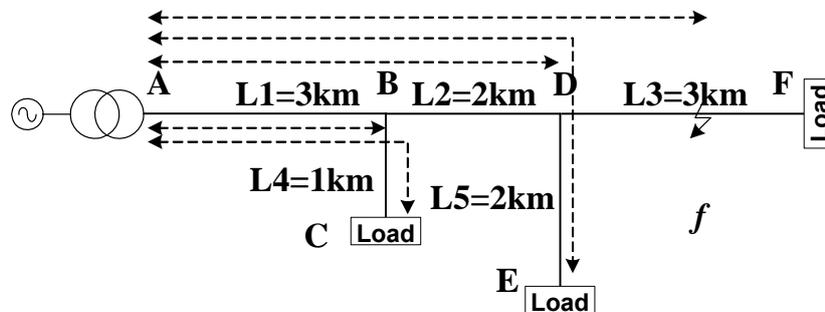


Figure 1. One typical distribution system

Once the frequencies of the recorded transient signal are identified, the fault position can be located based on equation (3).

### 3. Transmission Line Model in PSCAD/EMTDC

The following transmission line models have been provided in simulation softwares: multiple  $\Pi$  or T line model, Bergeron line model and frequency-dependent line model.

**3.1. Multiple Π or T Line Model**

The principle of distributed parameter circuit should be used to analyze the traveling wave propagation in transmission line. As shown in Figure 2, multiple Π or T line model is used and a short circuit fault happens at the end.

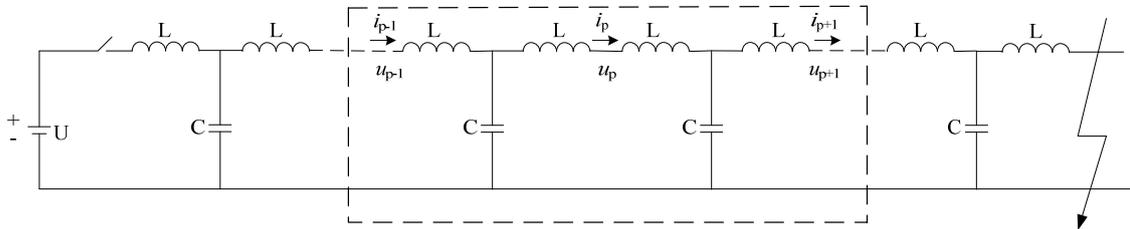


Figure 2. MultipleΠ or T line model

Assume equivalent inductance of the system is zero, from the analysis in [15], multiple Π line model and multiple T line model have the same difference equation, the voltage at the  $p^{th}$  chain of the line is as follows:

$$u_p(t) = U \left( 1 - \frac{p}{n} - \frac{1}{n} \sum_{k=1}^n \cot \frac{k\pi}{2n} \sin \frac{kp\pi}{n} \cos \omega_k t \right) \tag{4}$$

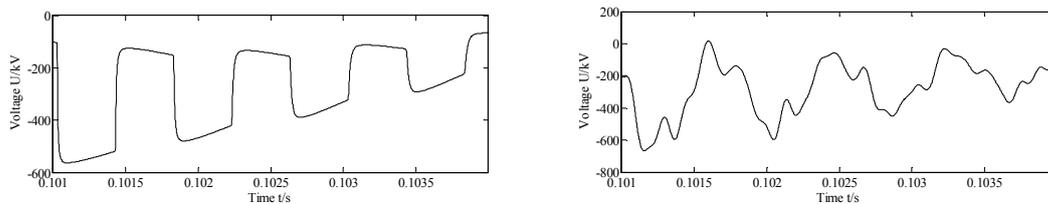
where:  $\omega_k = \frac{2}{\sqrt{LC}} \sin \frac{k\pi}{2n}$ .

The equation (4) shows that: 1) oscillation would happen in the chain network; 2) there exists  $n$  oscillating angular frequencies which equals the number of the chains. In digital simulation or dynamic physical simulation, number of the chains can't be infinite. Then it can't simulate the traveling wave front accurately and can't meet the test demand of the fault location algorithm based on wave-front identification as shown in Figure 3.

When  $n$  approaches to infinity, equation (5) can be derived and it is the basis of characteristic-frequency fault-location algorithm.

$$f_0 = \left[ \lim_{n \rightarrow \infty} \left( \frac{2}{\sqrt{LC}} \sin \frac{k\pi}{2n} \right) \right] / 2\pi = \frac{k}{2 * l * \sqrt{LC}} \tag{5}$$

Thus simulation results of multiple Π or T line model can't describe the actual wave-front characteristics and characteristic frequency of traveling wave because of the limited number of the chains.



(a) Traveling wave in Jmarti line model<sup>[16]</sup> (b) "Traveling wave" in multiple T line model  
Figure 3. Comparison of simulation results between Jmarti and multiple T line model

### 3.2. Bergeron Line Model

Assume parameters of the conductor are independent of frequency, Bergeron model can be used for transient calculation for lossless transmission line as shown in Figure 4. When line loss is taken into account, the total system resistance can be equivalent to lumped parameter ( $1/2$  in the middle of the line and  $1/4$  at each end).

Actually parameters are affected by frequency due to skin effect and it is the main reason of traveling-wave dispersion. The dispersion will be more obvious in zero-mode wave. For a three-phase transmission line, comparison of the simulation results between Bergeron model and Jmarti model in which dispersion is considered is shown in Figure 5 when a single phase-to-ground fault happens.

From the analysis mentioned above, Bergeron line model can't meet the test demand of the fault location algorithm based on wave-front identification because it ignores the traveling-wave dispersion. But traveling-wave propagation would be simulated accurately when the skin effect can be omitted. Because the frequency of the component used in fault location algorithm based on characteristic frequency is usually low and the algorithm doesn't need to recognize wave fronts [10]-[13], the dispersion has little affection on this algorithm. Thus Bergeron can be used to test the fault location algorithm based on characteristic frequency to some extent.

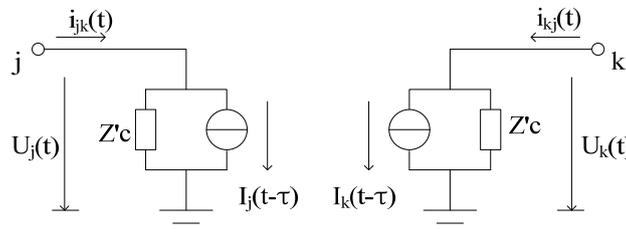
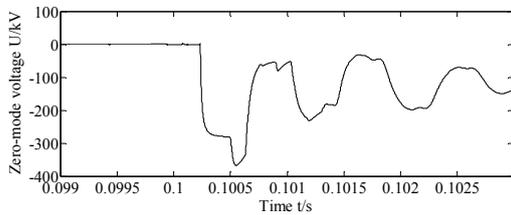
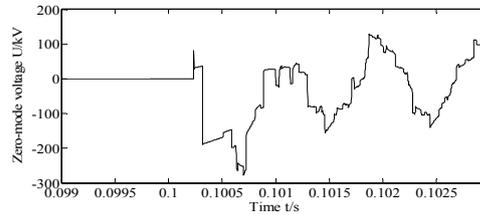


Figure 4. Bergeron line model



(a) Traveling wave in Jmarti line model



(b) Traveling wave in Bergeron line model

Figure 5. Comparison of simulation results between Jmarti and Bergeron line model

### 3.3. Frequency-dependent Line Model

When parameters of the conductor vary with frequency, the traveling wave propagation must be calculated in frequency domain while the electromagnetic transient calculation is easy to carry out in time domain. To solve this problem, one method is to utilize Fourier transform, another method is to treat the characteristic impedance and propagation coefficient with approximation by rational function based on Bode diagram [22] and etc.

The current on both sides of transmission line  $k-m$  is as follows:

$$\begin{cases} I_k = \frac{U_k}{Z_c} + I_{kh} \\ I_m = \frac{U_m}{Z_c} + I_{mh} \\ I_{kh} = -\frac{1}{Z_c}(U_m + Z_c I_m)A = -\frac{2F_m}{Z_c} A \\ I_{mh} = -\frac{1}{Z_c}(U_k + Z_c I_k)A = -\frac{2F_k}{Z_c} A \end{cases} \quad (6)$$

Where:  $I_k, U_k$  – current and voltage on the  $k$  side;  $I_m, U_m$  – current and voltage on the  $m$  side;  $Z_c$  – characteristic impedance;  $A$  – propagation coefficient,  $A = e^{-\sqrt{ZY}l}$ ,  $l$  – length of the line  $k$ - $m$ .

The line model proposed in [22] is the known Jmarti line model. In the paper two rational functions are utilized to simulate  $Z_c(\omega)$  and  $A(\omega)$ . The principle of this method is to use analog filtering technology to identify frequency-dependent parameters in fact. Based on this method, Jmarti line model is the common model used in traveling-wave fault location.

#### 4. Analyses of the Characteristic Frequencies

When the EDS operates normally and an impulse signal is injected at bus A, the characteristic frequencies of the recorded transient signal at bus A are called the inherent characteristic frequencies of the system.

Table 1. Inherent characteristic frequencies of the EDS showed in Figure 1

Propagation path	Length of the propagation length (km)	inherent characteristic frequencies (kHz)
A-B	4*3	25.00
A-B-C	2*4	37.50
A-B-D	4*5	15.00
A-B-D-F	2*8	18.75
A-B-D-E	2*7	21.43

Take the distribution system shown in Figure 1 as an example, and then the inherent characteristic frequencies can be calculated and shown in Table 1.

When a fault occurs in the electrical distribution system, the frequencies of the recorded signal at bus A will be different from the inherent characteristic frequencies. Take the fault at the middle of line DF shown in Figure 1 as an example, the recorded transient signal at bus A is shown in Figure 6.

The whole window of data, which is analyzed by Fast Fourier transform (FFT), contained 1ms of pre-fault and 1ms of post-fault data, and the results corresponding to the fault at middle of line DF are shown in Figure 7. Then the characteristic frequencies of 10.74 kHz and 24.41 kHz can be founded. But in theory, the characteristic frequencies can be calculated as follows: 25.00 kHz, 15.00 kHz, 37.50 kHz, 21.43 kHz and 11.54 kHz. So the big error exists in the extraction of frequencies, as same as the results mentioned in [10]-[12].

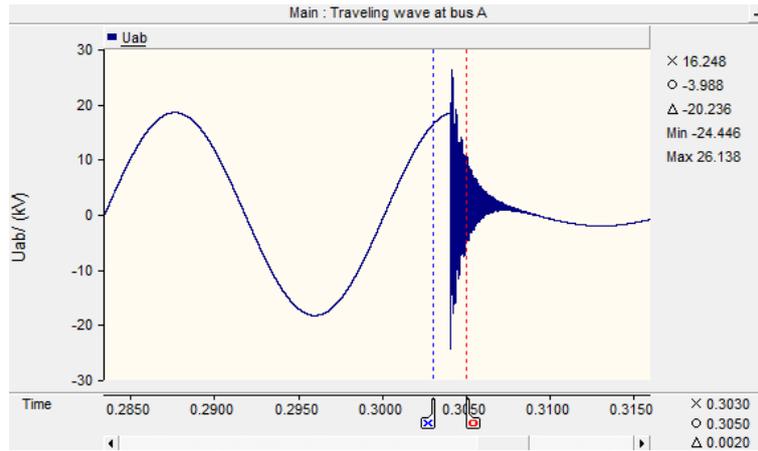


Figure 6. The recorded transient signal at bus A shown in Figure 1

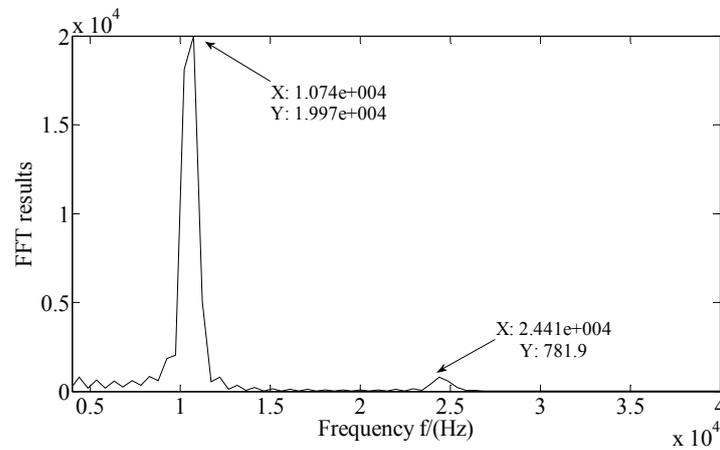


Figure 7. Frequencies of the recorded signal at bus A associated to the fault at middle of BC

**5. A Novel Fault Location Method Based on Characteristic Frequencies**

A novel fault-location method based on characteristic frequencies can be proposed. Firstly, FFT is used to extract the frequencies of the recorded signal. Secondly, the whole frequency is divided to several sub-frequency bands, and each sub-frequency band contain one of the inherent characteristic frequencies. Thirdly, the energy values of the sub-frequency bands can be calculated and normalized. Fourthly, the energy values corresponding to the typical fault positions can be obtained in advance. Finally, one a fault occurs, the following equation can be used to identify the fault position.

$$\min_j \sum_{i=1}^n (E_{if} - E_{ij})^2, j \in V \tag{7}$$

Where:  $V$  denotes the set of the typical fault positions in the priori database;  $j$  represents the  $j^{\text{th}}$  typical fault position;  $E_{if}$  represents the energy value of the  $i^{\text{th}}$  frequency sub-frequency band for the real fault;  $E_{ij}$  represents the energy value of the  $i^{\text{th}}$  frequency sub-frequency band for the  $j^{\text{th}}$  typical fault position and  $n$  represents the number of the frequency sub-frequency bands corresponding to the distribution system.

## 6. Conclusions

Digital simulations are important for the study of TWFLMs in EDSs. Using the Jmarti line model and the algorithms of digital signal processing provided in Matlab, the TWFLMs can be deeply discussed.

Because the fault-generated transient traveling wave must be transferred through transmission line, mutual inductor and secondary circuit before it is used, the modeling method of mutual inductor, including TA model, TV model and CVT model, need to be discussed in the future paper.

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